Course: ME 36100 – Kinematics and Dynamics of Machinery

Type of Course: Required for ME program

Catalog Description: Position, velocity, and acceleration analysis and design of machine elements including n-bar linkages, programmable mechanisms, and gear trains, dynamic force analysis and balancing of linkages; flywheels.

Credits: 3

Contact Hours: 3

Prerequisite Courses: ME 16000, ME 25100, and MA 36300

Corequisite Courses: None

Prerequisites by Topics: Machines, kinematics, dynamics, differential equations, motion simulation, displacement, velocity, acceleration, force, torque, power, Newton’s motion laws, vibration, computer aided design, linear equations, vectors, matrices.


Course Objectives: Understand the kinematics and dynamics of mechanical elements such as linkages, gears, and cams and learn to design such elements to accomplish desired motions or tasks.

Course Outcomes: Upon successful completion of this course, students should be able to:

a. Understand types of motion (a, e)
b. Understand types of joint (a)
c. Use degrees of freedom to analyze mobility conditions (a, e)
d. Construct and analyze vector loop equations (e)
e. Analyze forces and torques of components in linkages (a, e)
f. Understand static and dynamic balance (a)
g. Understand forward and inverse kinematics of open-loop mechanisms (a)
h. Apply computing tools to solve kinematic and dynamic problems (e, c, k)
i. Communicate effectively through reports and presentations

Lecture Topics

1. Machine kinematics (14 lectures)
   - Overview
   - Degrees of freedom
   - Links and joints
   - Grashof condition
   - 4-bar linkage, slider-crank, and inverted slider crank

2. Machine Dynamics (11 lectures)
   - Newtonian solution method
   - Force analysis of linkage
   - Shaking force and torque
   - Balancing linkage
   - Flywheels

3. Gears and gear trains (9 lectures)
   - Terminologies of gears and gear trains
   - Interface, undercutting, contact ratio
   - Simple gears and compound gear trains
   - Planetary gear trains

4. Cam systems (3 lectures)
   - Cam terminologies
   - Cam function design and sizing

5. Programmable mechanisms (8 lectures)
   - Introduction to industrial manipulators
   - Kinematic chains and classifications
   - Coordinate transformation
   - Forward and inverse kinematics

6. Exams (3 lectures)

Computer Usage
High

Laboratory Experience
None

Design Experience
Medium

Coordinator
Zhuming Bi, Ph.D.

Date
November 07, 2012